

# A model with $p$ -measures and no $p$ -point

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It is easy to see that  $d_{\mathcal{U}}$  extends asymptotic density.

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Let  $\mu$  be a measure on  $\omega$ . We say that  $\mu$  is a  $p$ -measure( $AP$ -measure or has  $AP$ -property), if for any  $\subseteq$ -decreasing sequence  $\langle A_n : n \in \omega \rangle \subseteq \mathcal{P}(\omega)$ , there is  $B \in \mathcal{P}(\omega)$  such that:

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**Remark.** The existence of  $p$ -points implies the existence of  $p$ -measures.

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- ① Make a countable support iteration of length  $\omega_2$  such that each step is of the form  $\mathcal{G}(\mathcal{F}^\omega)$ , where  $\mathcal{F} = \{A \subseteq \omega : \mu(A) = 1\}$ , where  $\mu$  is a measure on  $\omega$ ,

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- 4 This property is preserved along the iteration by the  $\omega^\omega$ -bounding property of the steps (once a  $p$ -measure is killed, it does not resurrect).



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**Remark.** The measure in the previous theorem still uses a  $p$ -point in its definition, although not so direct as in the  $\mathcal{U}$ -limit.

## Theorem(P. Borodulin-Nadzieja, C., A. Morawski)

It is consistent that there is a  $p$ -measure, there is no  $p$ -point, and  $2^{\aleph_0}$  is arbitrarily large. Moreover, it is consistent that no  $p$ -measure is a Dirac measure neither an ultrafilter density.

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Forcing with Random over Shelah's model? That's almost the case, we need a natural modification of Shelah's model as in the case of Mekler's model.

Definition(A. Blass, 1986).

Two filters  $\mathcal{U}, \mathcal{F}$  are said to be nearly coherent if there is a finite to one function  $f : \omega \rightarrow \omega$  such that  $f(\mathcal{U}) \cup f(\mathcal{F})$  generates a filter.

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- ② If  $\mathcal{F}_0$  is an ultrafilter and  $\mathcal{F}_1$  is just a filter, then they are nearly coherent if and only if there is a finite to one function such that  $f(\mathcal{F}_1) \subseteq f(\mathcal{F}_0)$ .



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Let  $\mathcal{F}_0$  and  $\mathcal{F}_1$  be two filters on  $\omega$ . The game  $\mathcal{G}(\mathcal{F}_0, \mathcal{F}_1)$  between Player I and Player II is defined as:

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Player II wins if and only if  $\{a_n : n \in \omega\} \in \mathcal{F}_0$  and  $\bigcup_{n \in \omega} F_n \in \mathcal{F}_1$ .



### Lemma(S. Shelah)

If  $\mathcal{F}_0$  is a selective ultrafilter,  $\mathcal{F}_1$  is a  $p$ -point, and they are not nearly coherent, then Player I has no winning strategy in the game  $\mathcal{G}(\mathcal{F}_0, \mathcal{F}_1)$ .



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This lemma needs still works if instead of  $\mathcal{F}_1$  being just  $p$ -filter instead of a  $p$ -point.

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- ② If  $\dot{\mathbb{Q}}$  is a  $\mathbb{P}(\mathcal{U})$ -name for a proper  $\omega^\omega$ -bounding forcing, then  $SP(\mathcal{U}) * \dot{\mathbb{Q}}$  forces that  $\mathcal{U}$  can not be extended to a  $p$ -point.

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In the proof of 3) we use the previous lemma about the game  $\mathcal{G}(\mathcal{V}, \mathcal{U})$ .

### Definition.

Let  $\mathbb{B}$  be the random forcing and  $\dot{U}$  a  $\mathbb{B}$ -name for an ultrafilter. For  $p \in \mathbb{B}$ , define  $\dot{U}[p] = \{A \subseteq \omega : p \Vdash A \in \dot{U}\}$ .

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Recall that a filter is  $\mathcal{F}$  if the quotient  $\mathcal{P}(\omega)/\mathcal{F}$  is ccc. Equivalently, if  $\mathcal{A} \subseteq \mathcal{F}^+$  is such that for any different  $A, B \in \mathcal{A}$   $A \cap B \in \mathcal{F}^*$ , then  $\mathcal{A}$  is countable.

Proof.

- 1 Assume otherwise  $\dot{\mathcal{U}}[p]$  is not saturated and let  $\langle \mathcal{A}_\alpha : \alpha \in \omega_1 \rangle \subseteq \dot{\mathcal{U}}[p]$  be such that for any different  $\alpha, \beta \in \omega_1$ ,  $A_\alpha \cap A_\beta \in \dot{\mathcal{U}}[p]^*$ .

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This proves that  $\dot{\mathcal{U}}[p]$  is saturated. □

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## Lemma

Let  $\mathcal{U}$  be a selective ultrafilter and  $\dot{\mathcal{V}}$  be a  $\mathbb{B}$ -name such that  $\mathbb{B} \Vdash \dot{\mathcal{V}}$  is a  $p$ -point.  
Then for all  $p \in \mathbb{B}$ ,  $\mathcal{U}$  and  $\dot{\mathcal{V}}[p]$  are not nearly coherent.



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- 7 Then  $D = \{p \leq p_0 : (\exists A \in h(\mathcal{U}))(p \Vdash h^{-1}[A] \notin \dot{\mathcal{V}})\}$  is dense below  $p_0$ .



- 8 Let  $\mathcal{A} \subseteq D$  be a maximal antichain below  $p_0$ , and for each  $p \in \mathcal{A}$ , let  $A_p \in h(\mathcal{U})$  be such that  $p \Vdash h^{-1}[A_p] \notin \dot{\mathcal{V}}$ .



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- 13 Thus, we have  $X \in h(\mathcal{U})$  and  $\omega \setminus X \in h(\dot{\mathcal{V}}[p_0])$ , which contradicts our initial assumption of  $h(\dot{\mathcal{V}}[p_0]) \subseteq h(\mathcal{U})$ .

## Theorem(P. Borodulin-Nadzieja, C., A. Morawski)

If ZFC is consistent, then there is a model such that:

- ① There is a  $p$ -measure.
- ② There is no  $p$ -point.
- ③ No  $p$ -measure is a Dirac measure neither an ultrafilter density.
- ④  $2^{\aleph_0} = \kappa$  for a predetermined regular cardinal  $\kappa \geq \omega_2$ .

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Then define  $\mathbb{P} = \mathbb{P}_{\omega_2} * \dot{\mathbb{B}}_\kappa$ . The model is  $V[G * H]$ , where  $G * H$  is  $\mathbb{P}$ -generic over  $V$ .



- ① Since  $\mathbb{P}_{\omega_2}$  is bounding, proper and preserves  $\mathcal{U}_0$ ,  $\mathcal{U}_0$  remains as a selective ultrafilter in  $V[G]$ , so by P. Borodulin-Nadzieja-Sobota theorem, there is a  $\rho$ -measure in  $V[G * H]$ .

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- ⑦ Then,  $\dot{\mathcal{F}}$  can not be a  $p$ -point.

Thank you very much!